# RotaCol® - Silverline

## 'ANALOG' Output Precision Contactless Rotary Position Sensors

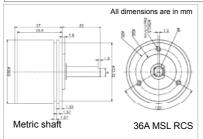
# **Servo Mount - 2 Precision Ball Bearings**

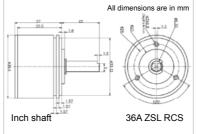
Metalcase - Hall effect magnetic

Output: 0 - 5V (ratiometric), 0 - 5V, 0 - 10V, 4 - 20 mA, 0 - 20 mA 36 mm Ø metal aluminium housing with 2 precision ball bearings Servo mount / Screw fitting

Shock & vibration proof, Measurement range 0° - 360°

- 1- Supply (Red); 2- Output (Yellow); 3- Ground (Black): For OCP
- 1- Supply (Red); 2- Output (Green); 3- Ground (Black): For OCG, OCR 1-Supply; 2-Output; 3-Ground: For OCM, OCTA, OCTR





## **ELECTRICAL CHARACTERISTICS**

Electrical angle	0 to 360°, any angle from 0 - 20 0 - 360		
Liectrical arigie	programmable in steps of 1 °		
Electrical speed (Max.)	160 rpm	(default) / 800 rpm (optional)	
Resolution		4096 step (12 bit)	
Independent linearity tolerance	± 0.5%		
Signal type	Supply voltage	Output signal	
S0505	5V ±10%	0 - 5V ratiometric	
SDC05	9 - 30 V	0 - 5V	
S2410	15 - 30 V 0 - 10 V		
S2442	15 - 30 V 4 - 20 mA		
S2420	15 - 30 V	0 - 20 mA	
S05052C	5V ±10%	2 channel 0 - 5V ratiometric	
SDC052C	9 - 30 V	2 channel 0 - 5V	
S24102C	15 - 30 V	2 channel 0 - 10 V	
Supply current	< 16 mA		
Update rate	1 ms		

## **MECHANICAL CHARACTERISTICS**

360° (continuous)	
Metric 6 mm Ø X 22 mm (MSL)	
Inch 1/4" Ø X 22 mm (ZSL)	
0.05 Ncm	
IP 40	
- 40 to +85° C	
40 million rotations	
8000 rpm	
60 gm	
3 pins (default)	

### **MATERIAL**

Housing	Anodized aluminium	
Shaft	Stainless steel	
Bearings	2 precision ball bearings	

# Series 36A MSL RCS Series 36A ZSL RCS

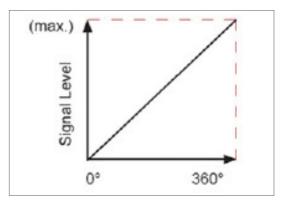


For full range of Rotary Sensor refer www.rotacol.info/rotamec.pdf

## **FUNCTION PRINCIPLE**

The determination of angular position and signal generation is realised by an intelligent CMOS Hall sensor. A diametrical polarised magnet induces its magnetic field into the sensor. It rotates and provides a conditioned signal to the integrated electronic.

# **ANALOG OUTPUT**



At the output of the sensor a variable voltage or variable current is provided proportional to the position of the shaft / axis over a complete angle range of 360 ° or a subrange. The contactless sensor electronic guarantees a steady signal level and a very low linearity error of 0.5%. With supply voltages of 5VDC  $\pm$  10%; 9 - 30VDC; 15 - 30V (24VDC) output signals of 0 - 5VDC; 0 -10VDC; 0 - 20mA; 4 - 20mA at the sensor output are provided. Besides this a large variety of electrical options such as Output signal level programming, Zero point programming, Centre point programming. Multipoint programming, two channel redundant outputs are provided. Other options on request.

## **Default Version:**

Servo mount, 36 mm housing with 2 precision ball bearing,360° CW Electrical & Mechanical angle, electrical speed 160 rpm, Output signal level 0-100%, 3 pins

A Analog output  Analog output  Analog output  Analog output  Analog output  Analog output  ESL  Inch Silverline (Shaft 6mm Ø)  RC  Substance (Shaft 144" Ø)  RC  Rotacol  O - 5V DC (ratiometric)  Substance (Substance (Shaft 6mm Ø)  O - 5V DC (ratiometric)  Substance (Substance (Subst
Analog output  Analog output  Metric Silverline (Shaff 6mm Ø  Inch Silverline (Shaff 1/4" Ø)  RotaCol  Servo mount with 2 ball bearing  Signal  0 - 5V DC (ratiometric) 0 - 5V DC (ratiometric) 2 channel 0 - 5V DC (ratiometric) 3 channel 0 - 5V DC (ratiometric) Counter clockwise (CCW) Direction of Rotation Clockwise (CW)- (default) Counter clockwise (CCW)  Direction of Rotation Clockwise (CW)- (default) Counter clockwise (CCW)  Direction of Rotation Clockwise (CW)- (default) Counter clockwise (CW)  Delta 1/2 Low level High level Variable level Vari
Housing diameter  Analog output  Analog output  thic Silverline (Shaff 6mm Ø output Silverline (Shaff 1/4" Ø)  RotaCol  o - 5V DC (ratiometric)  o - 5V DC (ratiometric)  o - 5V DC (ratiometric)  c - 10V DC  4 - 20mA  channel o - 5V DC (ratiometric)  2 channel o - 5V DC  4 - 20mA  o - 5V DC  o - 10V DC  4 - 20mA  channel o - 5V DC  default 360')  Direction of Rotation  Clockwise (CW)- (default)  Counter clockwise (CW)- (default)  Counter clockwise (CW)- (default)  Direction of Rotation  Clockwise (CW)- (default)  Counter clockwise (CW)- (default)  Coutput signal level  Variable leve

Example with description - **36A MSL RCS S2442 180CW PE1 POZ OCM -** 36mm diameter, analog output, Metric Silverline (Shaft 6 mm Ø), RotaCol, Servo mount with 2 ball bearings, Signal - 4-20 mA, 180 angle clockwise, Delta 1/2, Zero point, Miniature connector

## **ELECTRICAL OPTIONS FOR ANALOG VERSION 36A MSL/ZSL RCS**

## **Electrical options for Effective electrical angle:**

Electrical angle (xxx): Standard configuration is 360°. As an option, any angle from 0-20° to 0-359° in steps of 1° can be programmed. (Price adder)

Output Signal level Programming (POL): Standard configuration is 0-100%. Output signal can be programmed at any defined lower limit or upper limit in terms of percentage of output. Example: 10% to 90% for S0505 will give output from 0.5V to 4.5V (Price Adder).

# Direction of Rotation (CW/CCW):

CW(Clockwise) When shaft is viewed from top, and rotated in clockwise direction, output increases from minimum to maximum value(standard configuration).

CCW(Counter clockwise) when shaft is viewed from top, and rotated in counter clockwise direction, output increases from minimum to maximum value(Price adder).



## Zero point Programming (POZ) :

Standard configuration is zero point without orientation. At POZ, when we do zero point programming rising ramp will start from marking on encoder housing or from the endstop CCW. Zero point can also be programmed at any defined offset from marking on the housing (Price Adder).



## Center Point Programming (POC):

Effective electrical angle is aligned with the mechanical zero point in such a way that equal effective angles in both rotating directions are achieved. Center point can also be programmed at any offset (Price Adder).



## Multi Point Programming (POM):

Output characteristics: 3 to 6 rising or falling linear segments. Minimum and maximum signal level can be defined within the total electrical angle. First and last linear segment (min./max.) is always horizontal 1 to 3 setable calibration points. (Price Adder)



# Electrical options for Non - Effective electrical angle (Price Adder) : ( If electrical angle is < 360°)

# Delta 1/2 (PE1):

If the electrical effective angle is programmed smaller than 360°, the remaining non-effective electrical angle is divided in two equal parts: high level & low level - Delta 1/2.



## Low level (PE2):

If the electrical effective angle is programmed smaller than 360°, after reaching the maximum, the signal level falls to low level.

# 0° 360°

## High level (PE3):

If the elecrical angle is programmed smaller than 360°, the signal level remains high after reaching the full level.

# max. 9 360°

# Variable level (PE4) :

If the electrical angle is programmed smaller than 360°, remaining non-effective electrical angle can be divided into high and low level in any ratio according to customer request.



## 2 Channel Redundant Output (2C) - Special type

**2 Channel Output (2C)**: The sensor provides 2 operating modes: A) Redundancy i.e. channel one and channel two are identical. If one channel fails the other channel remains active.B) It is also possible to have 2 different programs in the 2 channels. For this, additional functions can be obtained.



## MECHANICAL OPTIONS FOR ANALOG VERSION 36A MSL/ZSL RCS

Type / Series	Standard mechanical options	Customized mechanical options
36A MSL/ZSL RCS	Cable gland (OCG), Round cable(OCR), Miniature connector (OCM), Terminal block (OCTA / OCTR)	Special shaft length; special cable length

# **INTERCONNECTIONS**

## Standard Interconnections - 3 pins

## Other Interconnection options

Cable gland (OCG)

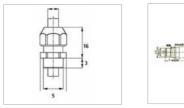
Miniature connector (OCM)

Terminal block - Axial (OCTA) Wires leaving axial to shaft axis

3 sockets

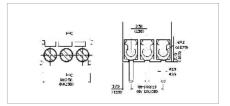
Terminal block - Radial (OCTR) Wires leaving radial to shaft axis

3 core round cable 1 m long



3 pin in integrated socket with plug

3 sockets



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